Eclipse Foundation & openADx Automotive Tools & Infrastructure

Mike Milinkovich Executive Director 2018-04-13

The Eclipse Foundation

350+ Projects

275+

Corporate Members

1500+ Committers

30 Professional Staff

By the Numbers





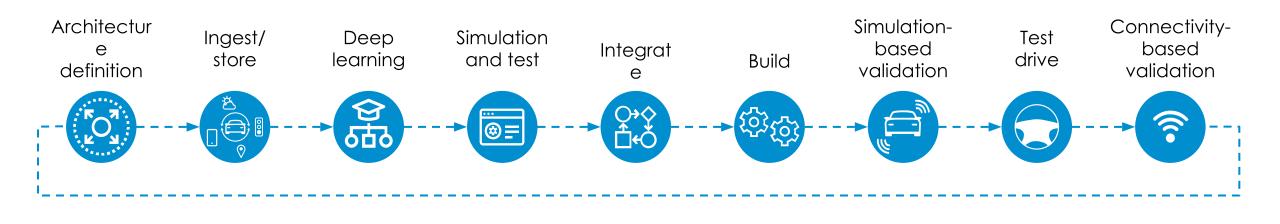
Trust Across the Lifecycle

- Software provenance
 - What is actually running on your device
- Software safety
 - Knowing what the software will do
- Data provenance
 - We use data to teach our machine learning systems
 - Data poisoning



4

Focus: AD Toolchain



GOAL

Industry-wide accepted definition of the AD toolchain

- > Foundation for reference architecture
- > Key to ensure efficient implementation and interoperability



Eclipse openPASS – an open source approach to safety impact assessment via simulation

Jan Dobberstein, Jörg Bakker (Daimler AG), Lei Wang, Timo Vogt (BMW AG), Michael Düring, Lukas Stark (Volkswagen AG), Jason Gainey (VW GoA), Alexander Prahl (ITK Engineering GmbH), Ralph Müller, Gaëlle Blondelle (Eclipse)



ESV Conference, Detroit, 08.06.2017

What is openPASS?



Accident research & safety system development

Need to assess functions with virtual simulation

Common simulation platform & harmonized modules



"open Platform for the Assessment of Safety Systems"

"The openPASS Working group wants to foster and support an open and innovative eco-system providing tools, systems, and adapters for standardized, openly-available and vendor-neutral platform for simulation of traffic scenarios."





Prospective evaluation of safety systems

Goal of prospective evaluation of safety systems – independent of methods, data and tools:

What are the effects of safety systems and automated driving functions with regard to safety?

- "True positives": reduction of conflicts and accidents, reduction of accident severity
- "False negatives": which accidents cannot be addressed / detected early enough?
- "False positives / true negatives": how to achieve high specificity e. g. by avoiding false positives?

openPASS aims to unify various virtual assessment approaches on one platform:

Accident re-simulation rake Assist	Traffic simulation Active Blind	Scenario variation
+ only relevant situations	+ full scope of scenarioasive Steering	+ controllable variation
+ fewer models needed	+ arbitrary variation/runs	+ combine various models
- missing information	- traffic model validation	- harmonization efforts

Eclipse SUMO – what is it?

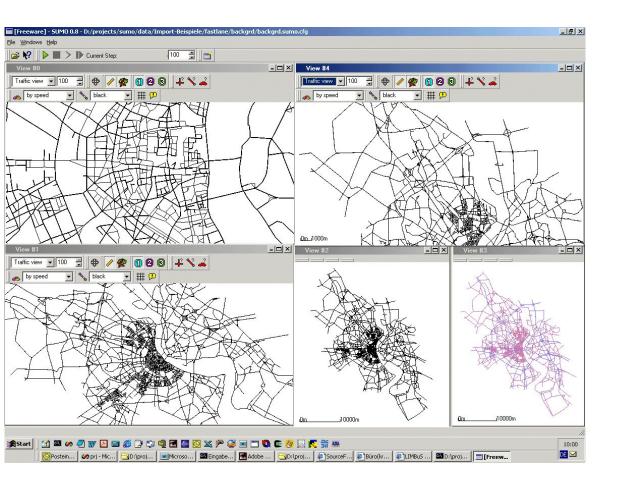
- DLR's open source microscopic transportation system simulation software
- Current version 0.30.0
- Under development since 2001, with the explicit goal to simulate even large cities / areas in real-time
- Current limitation: the city of Berlin



- SUMO comes with a full-fledged suite of helper programs that do setting up, running, and controlling such a simulation
- Most important of those tools is TraCI which allows to control a running SUMO simulation from outside via programs in various languages
- Active community with roughly 30,000 downloads annually, and about 1,000 requests on the mailing list.



Eclipse SUMO – components



- SUMO: Simulation without graphical Interface
- SUMO-GUI: Simulation with graphical Interface
- NETCONVERT: Importer for road networks
- OD2TRIPS: Importer for O/D matrices
- JTRROUTER: Router based on junction turning percentages
- DUAROUTER: Router based on dynamic user assignment





OPEN INTERFACES AND PROTOCOLS



Eclipse Kuksa Open Source Connected Car Platform

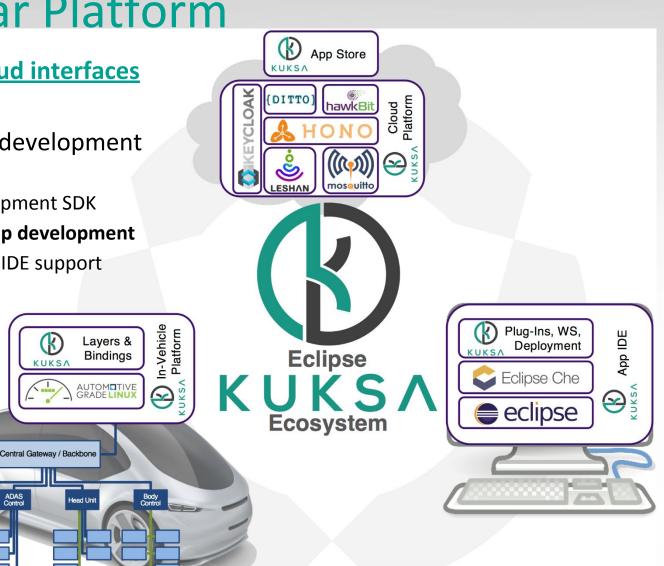
- Establishment of standardized vehicle IoT and Cloud interfaces to and from the vehicle
- Eclipse-Che-based <u>App IDE</u> to simplify & speed-up development activities
 - Use & enhance Automotive Grade Linux (AGL) App development SDK
 - Full-blown IDE for Kuksa-AGL App & Springboot Cloud App development

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KUKSA

ADAS Control

- Simplify the usage of automotive APIs integrated through IDE support
- Service enablers for car-to-cloud connectivity
 - Network infrastructure considerations
 - Next generation mobile networks
- Open source <u>in-vehicle platform</u>
 - Safe and secure gateway to the cloud
 - In-vehicle data access mechanism and application platform



OpenADx – Open Automated Driving Accelerator Xcelerate your AD development

Automated driving is a complex challenge

> AD requires a multifaceted development process incorporating a variety of software tools

> But none of these tools were ever designed to work together

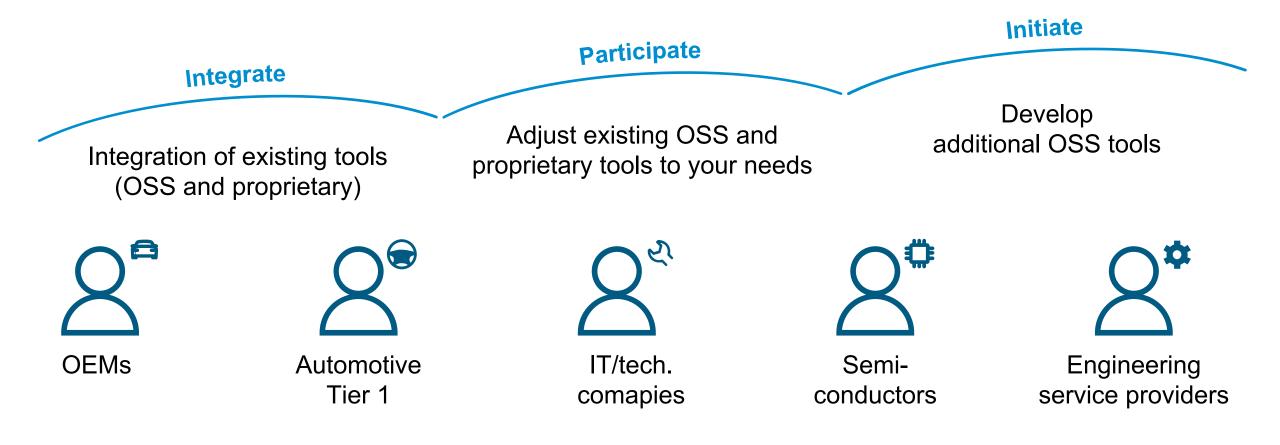
> This costs us all time and money

> We oppose this by creating the leading automated driving ecosystem \succ OpenADx

> Thereby, we leverage open collaboration and open source to

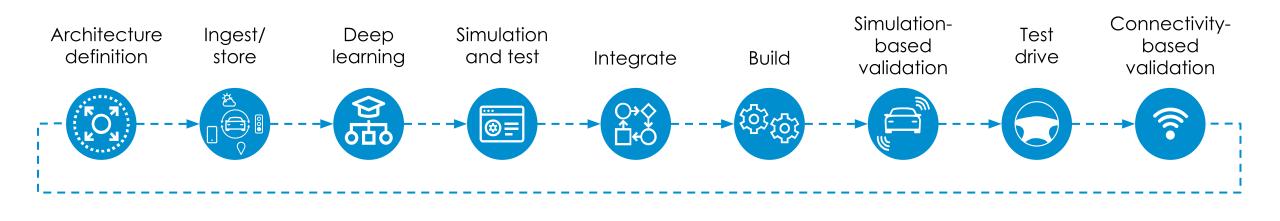
- Accelerate time to market
- Increase efficiency
- Focus on customers

OpenADx Beneficial for OEMs, Tier1s and technology providers The AD tool chain: Seamless integration and increased development efficiency



(15)

Focus: AD Toolchain



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(17)

From testbed to open source and standardization

Testbeds

>Validation of solution blueprint, often combination of exiting products/technologies
>Small, loosely coupled ecosystem of partners who play well together
>Usually strong Go-To-Market focus (example: IIC Track & Trace, first customer in <12 months)

Open Source Project

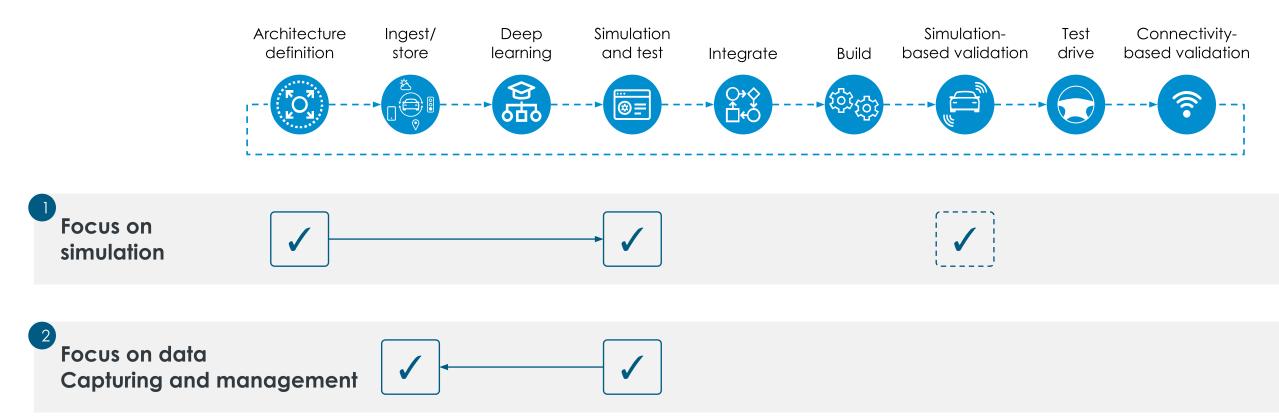
Result of a testbed can be a joint open source project
Sometimes new solutions
Sometimes the "glue" required to tie together existing solutions

Standardization

Often focusing on the APIs developed in the OSS project
Usually slower moving

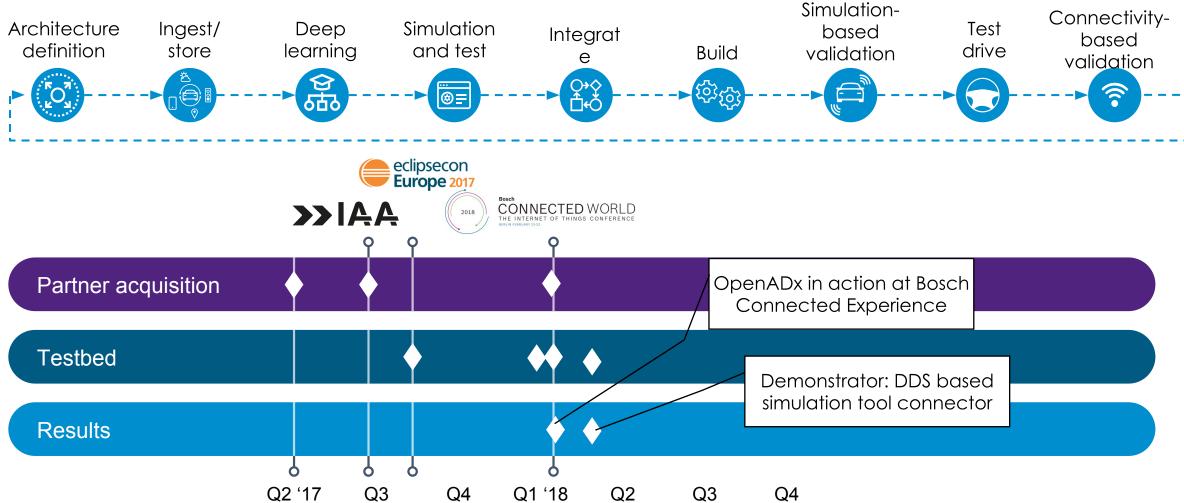
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Testbed/incubator portfolio



Timeline

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Thank-you!

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Thank you!

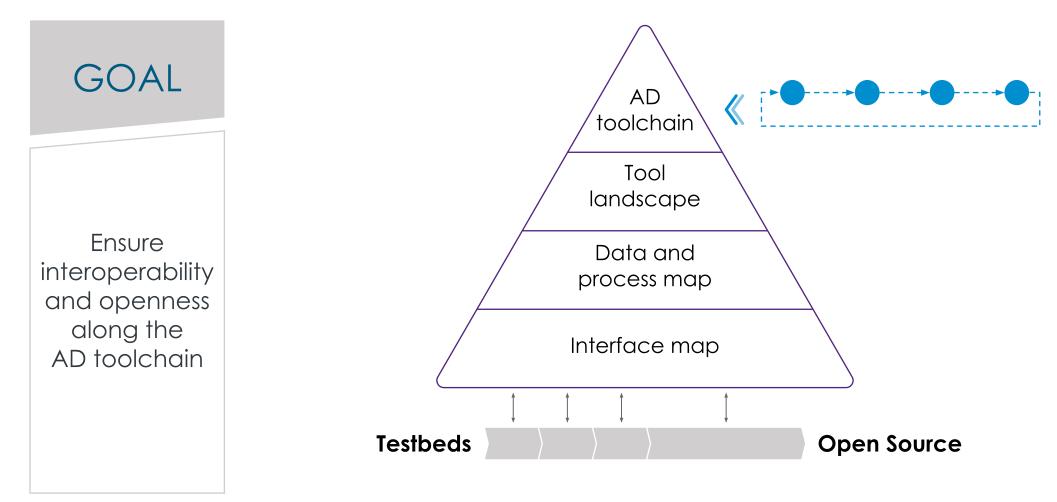
Charles Degutis Charles.Degutis@de.bosch.com Andreas Riexinger Andreas.Riexinger@de.bosch.com

Find out more and join us https://wiki.eclipse.org/OpenADx

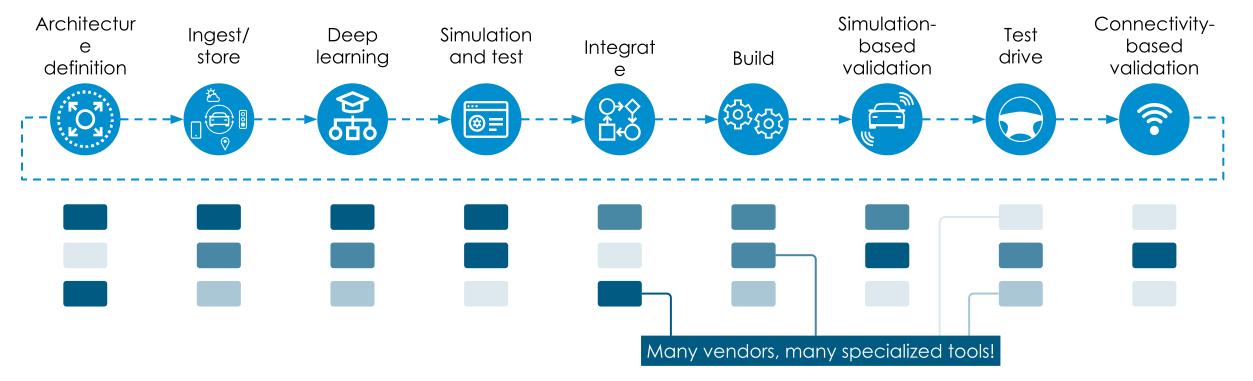
BACKUP

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Focus: AD Toolchain Framework



Focus: Tool Landscape

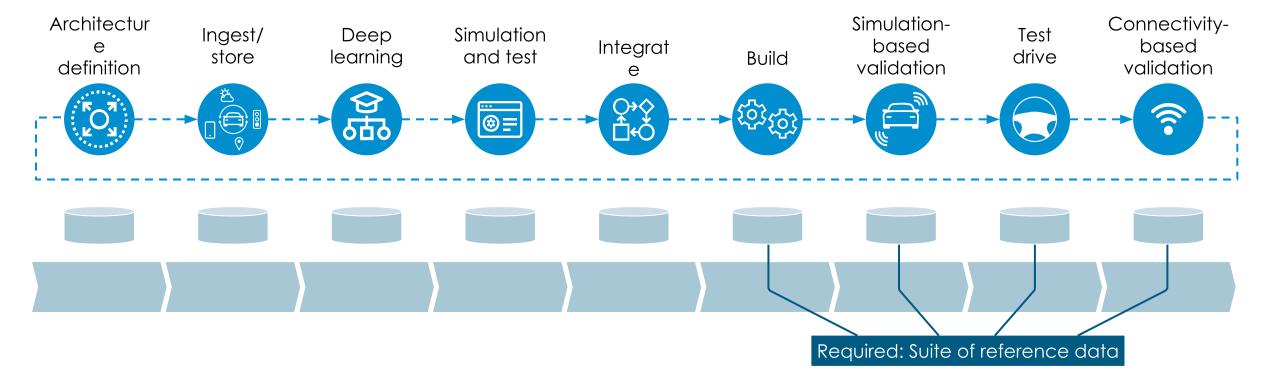


GOAL

 Ensure transparency and make complex tool landscape more easily accessible for enterprise users

Focus: Data and Process Map





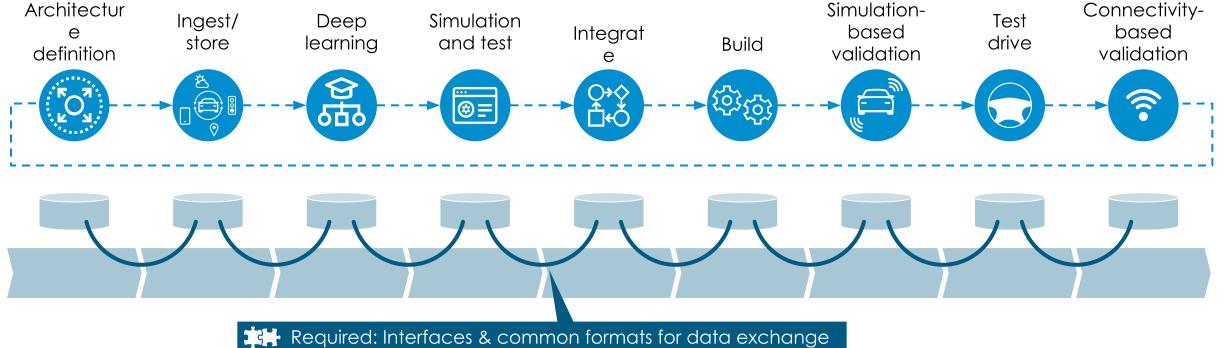
GOAL

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> Prepare for easy data exchange and process interoperability between different tools

Focus: Interface Map





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> Enable easy data exchange and process interoperability between different tools

Summary

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